

DATE: Wednesday, September 10, 2003 Printable Copy Create Case





Set Name side by side	Query	Hit Count	Set Name result set
DB=USPT,PGPB,JPA	AB,EPAB,DWPI,TDBD; PLUR=YES; OP=AD.	I	
<u>L24</u>	L23 and 120	4	<u>L24</u>
<u>L23</u>	L22 near 121	15557	<u>L23</u>
<u>L22</u>	force	2002111	<u>L22</u>
<u>L21</u>	damp\$3	294328	<u>L21</u>
<u>L20</u>	L19 and 110	126	<u>L20</u>
<u>L19</u>	L18 or 114	4521	<u>L19</u>
<u>L18</u>	L17 or 115 or 116	2458	<u>L18</u>
<u>L17</u>	under near steer\$3	1290	<u>L17</u>
<u>L16</u>	under-steer\$3	362	<u>L16</u>
<u>L15</u>	understeer\$3	1250	<u>L15</u>
<u>L14</u>	L13 or 112 or 111	3131	<u>L14</u>
<u>L13</u>	oversteer\$3	1341	<u>L13</u>
<u>L12</u>	over-steer\$3	420	<u>L12</u>
<u>L11</u>	over near steer\$3	1907	<u>L11</u>
<u>L10</u>	18 and 15 and 19	203	<u>L10</u>
<u>L9</u>	steering angle	17436	<u>L9</u>
<u>L8</u>	L7 near 16	65769	<u>L8</u>
<u>L7</u>	speed or velocity	2317802	<u>L7</u>
<u>L6</u>	vehicle	1378510	<u>L6</u>
<u>L5</u>	L4 near4 13	339	<u>L5</u>
<u>L4</u>	compar\$3	1832161	<u>L4</u>
<u>L3</u>	11 near 12	4717	<u>L3</u>
<u>L2</u>	rate	1835904	<u>L2</u>
<u>L1</u>	yaW	18001	<u>L1</u>

END OF SEARCH HISTORY



T tal Assignments: 1

Application #: 10033870 Filing Dt: 12/28/2001 Patent #: NONE Issue Dt:

PCT #: NONE Publication #: 20030047994 Pub Dt: 03/13/200

Inventor: You-Seok Koh

Title: Method for controlling a damper of a vehicle

Assignment: 1

Reel/Frame: 012437/0615 Received: Recorded: Mailed: 03/04/2002 Pages:

Conveyance: ASSIGNMENT OF ASSIGNORS INTEREST (SEE DOCUMENT FOR DETAILS).

Assignor: KOH, YOU-SEOK Exec Dt: 12/24/2001

Assignee: MANDO CORPORATION

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KYONGGI-DO 451-821, KOREA, REPUBLIC OF

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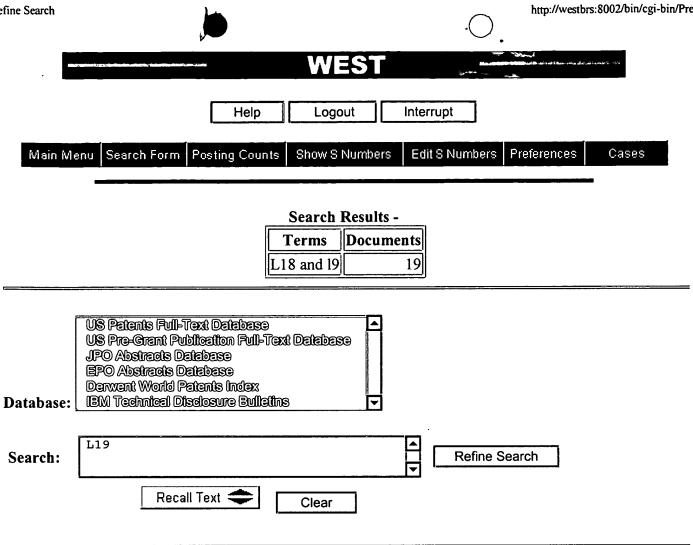
1251 AVENUE OF THE AMERICAS

43RD FLOOR

NEW YORK, NY 10020-1182

Search Results as of: 9/10/2003 9:03:57 A.M.

If you have any comments or questions concerning the data displayed, contact OPR / Assignments at 703-308-9723 Web interface last modified: Oct. 5, 2002



Search History

DATE: Tuesday, September 09, 2003 Printable Copy Create Case

Set Name side by side	Query	Hit Count	Set Name result set
DB = USPT, PGPB,	JPAB,EPAB,DWPI,TDBD; PLUR=YES; OP=ADJ		
<u>L19</u>	L18 and 19	19	<u>L19</u>
<u>L18</u>	L17 and 116	1068	<u>L18</u>
<u>L17</u>	114 or 113 or 110	3131	<u>L17</u>
<u>L16</u>	L15 or 112 or 111	2458	<u>L16</u>
<u>L15</u>	under-steer\$3	362	<u>L15</u>
<u>L14</u>	over-steer\$3	420	<u>L14</u>
<u>L13</u>	oversteer\$3	1341	<u>L13</u>
<u>L12</u>	understeer\$3	1250	<u>L12</u>
<u>L11</u>	under near steer\$3	1290	<u>L11</u>
<u>L10</u>	over near steer\$3	1907	<u>L10</u>
<u>L9</u>	L8 and 17 and 13 and 16	54	<u>L9</u>
<u>L8</u>	14 near3 15	92825	<u>L8</u>
<u>L7</u>	11 near3 12	4983	<u>L7</u>
<u>L6</u>	"damping force"	13050	<u>L6</u>
<u>L5</u>	velocity or speed	2317802	<u>L5</u>
<u>L4</u>	vehicle	1378510	<u>L4</u>
<u>L3</u>	"steering angle"	17436	<u>L3</u>
<u>L2</u>	rate	1835904	<u>L2</u>
<u>L1</u>	yaw	18001	<u>L1</u>

END OF SEARCH HISTORY